



Project funded by the **EUROPEAN UNION**





A Location-aware System for Fruit Fly Monitoring and Pest Management Control

Wireless Sensor Network architecture and Web Services







Universitat de les Illes Balears

UIB







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AUA Olive Fruit Fly Net LAS Components



- 5 Nodes
- 10 Raspberry Pi 2+
- 10 Cameras
- 1 Router
- 1 GSM SIM card



- 5 Temperature Sensors
- 5 Humidity Sensors
- 1 Anemometer
- 1 Rain gauge





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AUA Olive Fruit Fly Net LAS Network Issues

- Equipment malfunctions
- Router loss of internet connectivity
- Corrupt photos
- Raspberry loss of wireless connectivity
- Data loss due to connectivity issues
- Raspberry OS freeze
- Need for remote management



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AUA Olive Fruit Fly Net LAS Network Issues - Resolution



- Router loss of internet connectivity
 - Communication with provider to fine tune connection parameters
 - Scheduled router to restart daily
- Corrupt photos
 - Increased the sampling ratio of photos
- Raspberry loss of wireless connectivity
 - Scheduled wi-fi reset prior to data transmission
 - Scheduled raspberry soft reset





AUA Olive Fruit Fly Net LAS Steps for issue resolution



- Data loss due to connectivity issues
 - > Each raspberry keeps its own set of scalar data and photo
 - Each raspberry stores failed transmissions and attempts to upload them to the server with the next data upload
- Raspberry OS freeze

Scheduled raspberry soft reset

• Remote management

Used a free VPN solution, that provides a direct secure tunnel connection to the raspberries.





AUA Olive Fruit Fly Net LAS Web Services – Server Communication



Each raspberry is scheduled to take photos and sensors readings at specified intervals.

The raspberry then proceeds with uploading the scalar data using web services and the photos with the use of ftp.

In order to mitigate network traffic load, the schedule of each raspberry varies slightly from the others.

50 0,3,6,8,10,12,14,16,18,20,22 * * * /home/pi/SensorData.py

0 7,10,14,16 * * * /home/pi/CaptureUploadPhoto.sh

55 6,9,13,15,21 * * * sudo /sbin/shutdown -r now

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